Zagreb, Real-Time Systems

RIOT OS & LoRa with RIOT OS

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sartura

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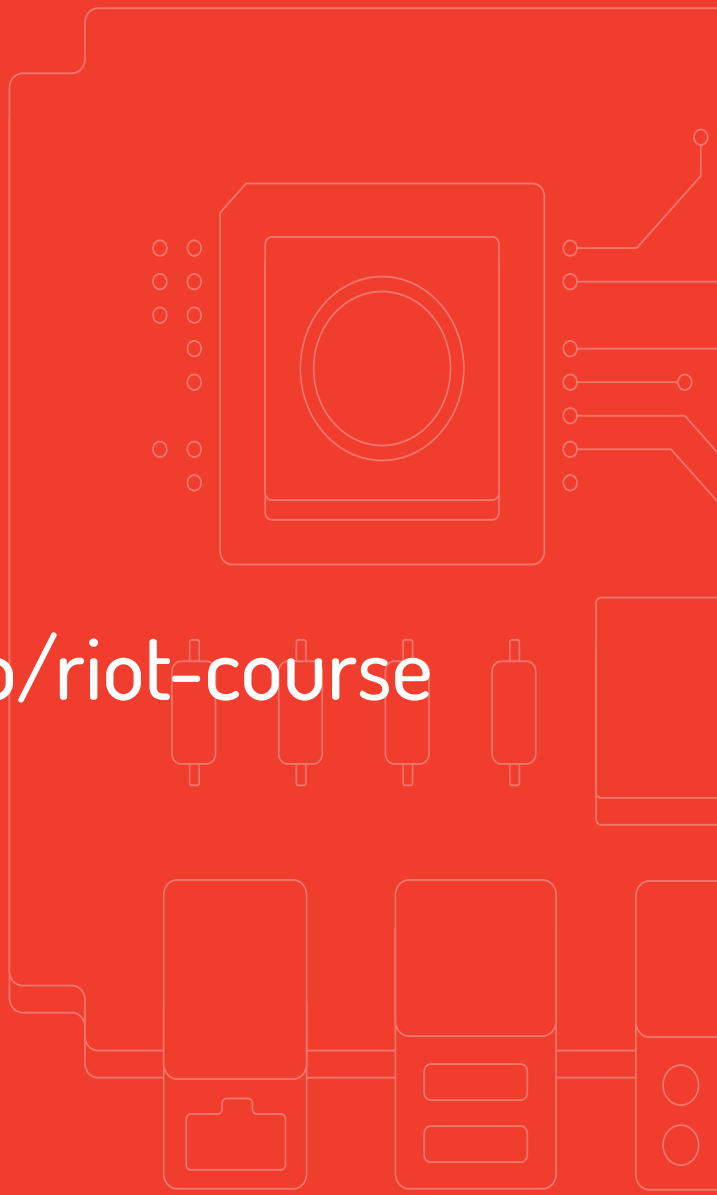
About us

- Juraj Vijtiuk, Luka Paulić
- Delivering solutions based on Linux, OpenWrt and Yocto
  - Focused on software in network edge and CPEs
- Continuous participation in Open Source projects

RIOT OS

Based on https://aabadie.github.io/riot-course



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Introduction

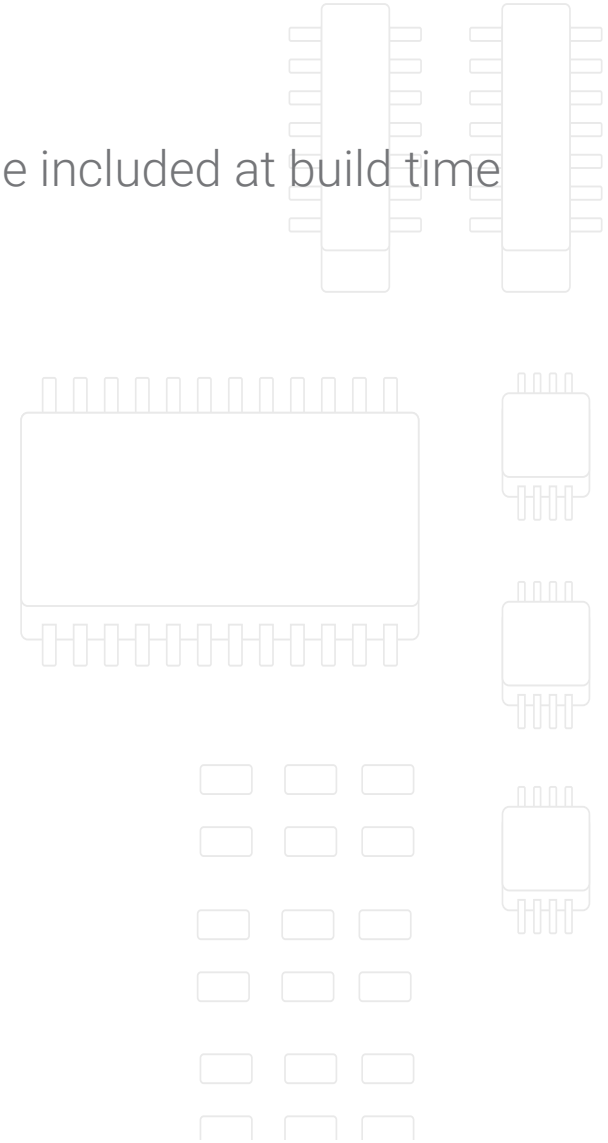
- Operating system for embedded devices with a focus on IOT
  - Microkernel, real time, multithreaded
  - Support for 8-bit, 16-bit and 32-bit MCUs
  - Unified API, independent of the underlying hardware
  - Mostly POSIX compliant

- Open Source
  - LGPLv2.1 licence
  - https://github.com/RIOT-OS/RIOT
  - Active community, started at Inria, FU Berlin and HAW in 2013
- Written in C
- Verbose official documentation

Features

- Real time scheduler
  - Preemptive, tickless O(1) scheduling with priorities
- Support for over 100 boards
  - Native board allows RIOT to run as a process on Linux, BSD and Mac
  - Multiple native instances can be connected via virtual bridges
- Generic API for CPU peripherals
  - Gpio, uart, spi, pwm
  - Identical API for all architectures

- Build time configurable modules
  - Driver support for sensors and actuators can be included at build time
  - System libraries: shell, crypto, xtime
  - Network stacks: LoRaWAN, Sigfox, CoAP, IPv6
  - Support for external packages
- A large number of available example applications



Building a simple RIOT application

- RIOT uses GNU make as the default build system
- All applications use a single Makefile which then includes the main Makefile.include RIOT makefile
- `make flash`, `make term`, `make debug`
- Example:

```
1  APPLICATION = example
2  BOARD ?= native
3  RIOTBASE ?= $(CURDIR)/../../../RIOT
4  DEVELHELP ?= 1
5  include $(RIOTBASE)/Makefile.include
```

- `USEMODULE`
  - Support for shell as a module
- `USEPKG`
- `FEATURES_REQUIRED`
- Example:

```
1 USEMODULE += xtimer shell
2 USEPKG += semtech-loramac
3 FEATURES_REQUIRED += periph_gpio
```

Accessing hardware

- Access at 3 levels
  - Board
  - CPU
  - Driver
- Hardware layer separation is reflected in the source code
  - `boards/`, `core/`, `cpu/`, `drivers/`, `pkg/`, `sys/`, `tests/`
- E.g. xtimer

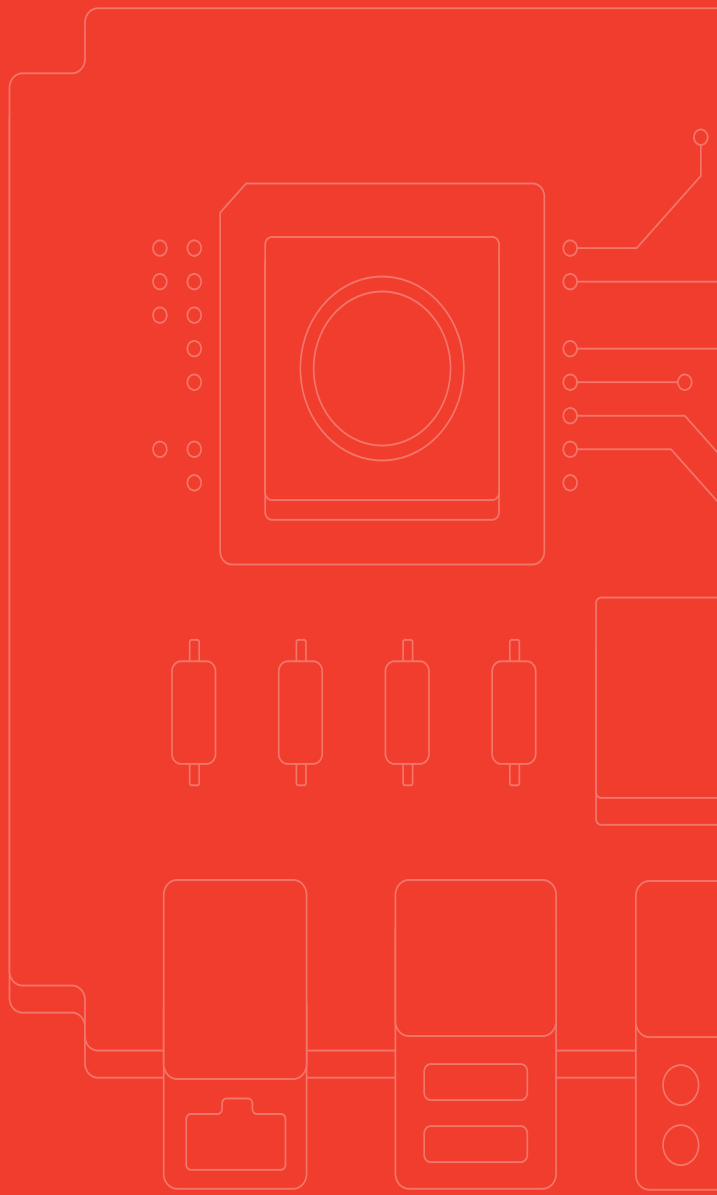
Multithreading

- Tick-less O(1) scheduling
- Highest priority thread runs until finished or interrupted
- Idle thread
  - Power management
- Threads are functions with separate stacks
- Support for synchronization mechanisms and IPC
  - Mutexes, semaphores, other POSIX mechanisms
  - Synchronous & asynchronous messaging

Networking

- Multiple network stacks available
  - IPv6: gnrc, LwIP, emb6
  - BLE, CAN, LoRaWAN
- Sock API
- IPv6 utility library
- POSIX socket API

LoRa with RIOT OS



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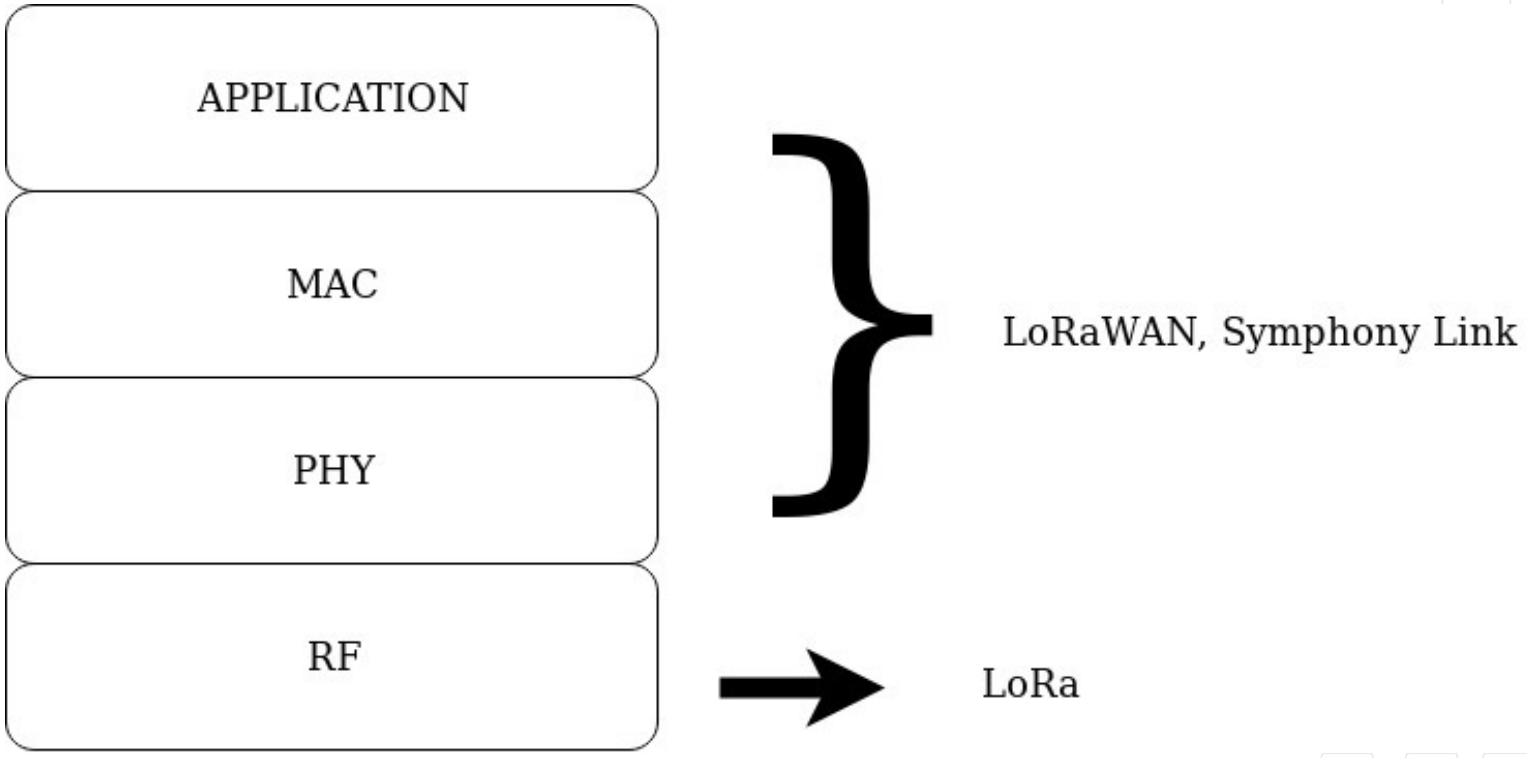
What is LoRa

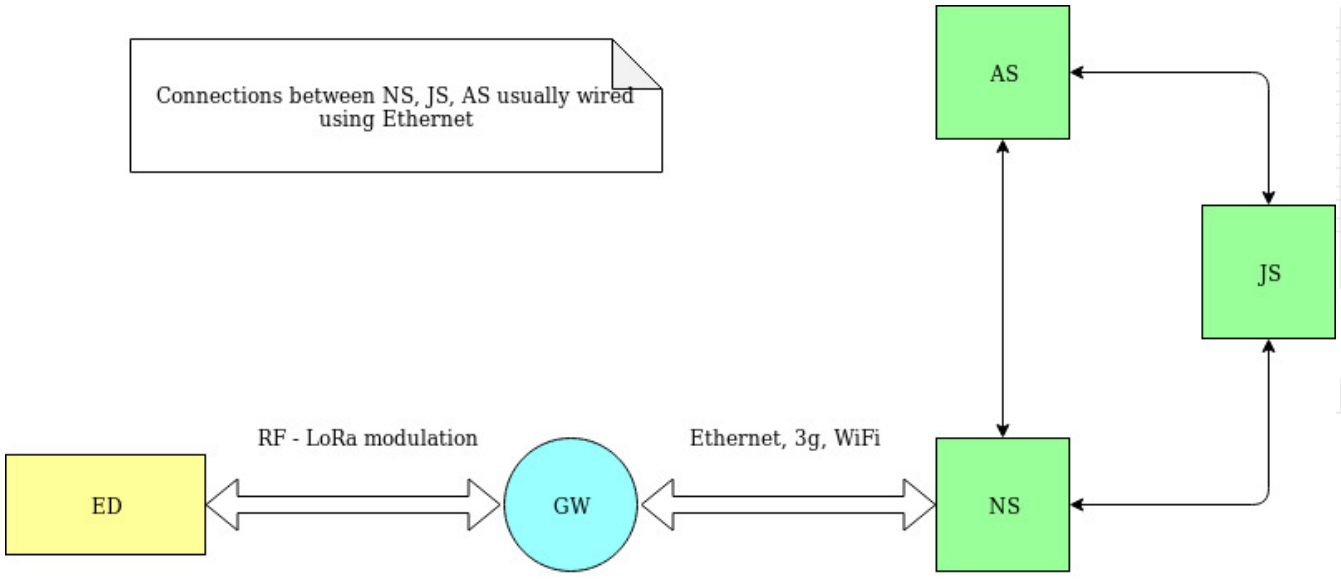
- LoRa - Long Range
- Acquired by Semtech in 2012.
- CSS modulation
- ISM frequency band

- Pros
  - Long range; >10 km
  - Low power; <= 10 years
- Cons
  - Low data rate; 300 bps - 50 kbps
  - Small data size; ~10 B
  - Regional restrictions
- IoT

LoRa protocol stack

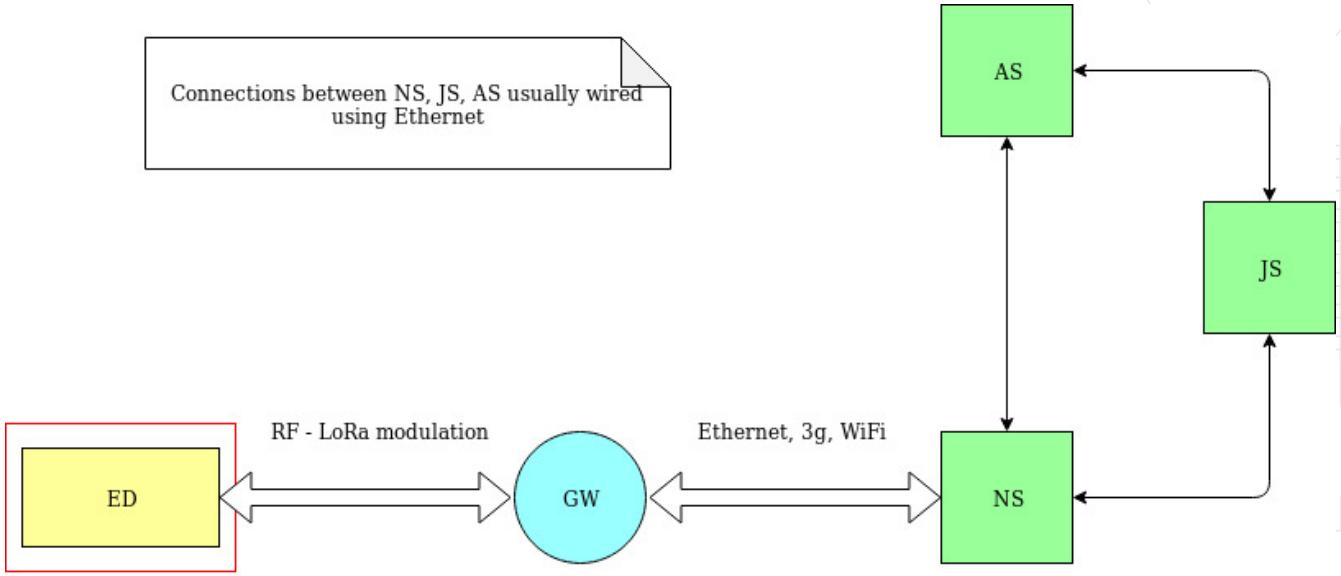


LoRa network architecture



Descripiton:

- ED => end device
- GW => LoRa gateway
- NS => network server
- JS => joint server
- AS => application server



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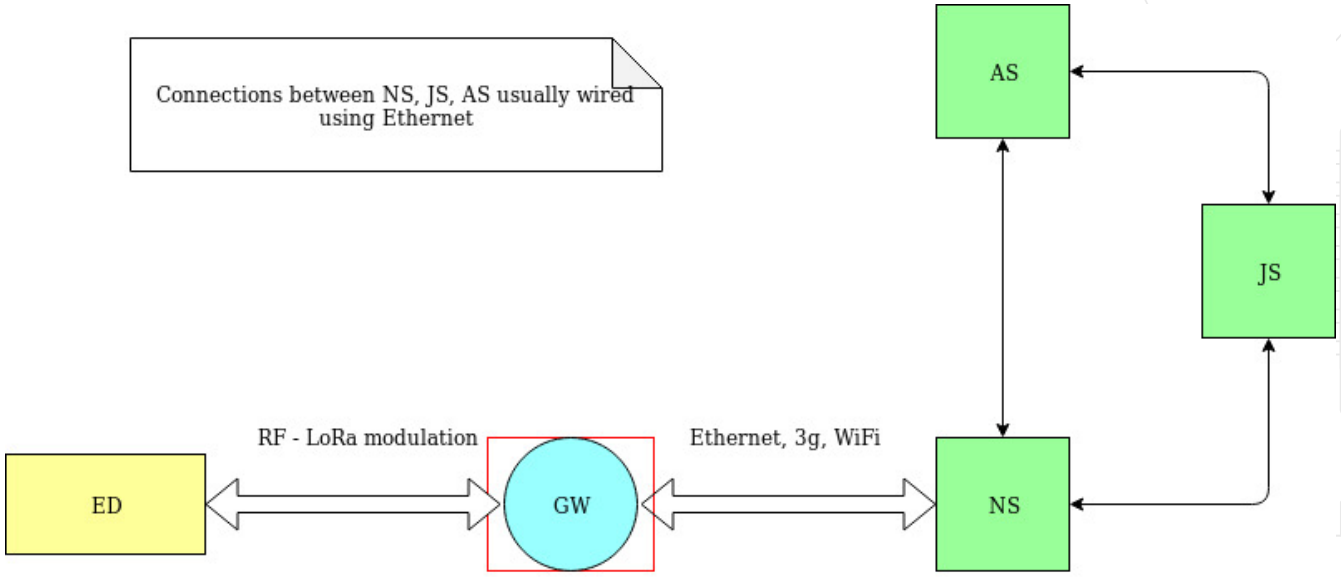

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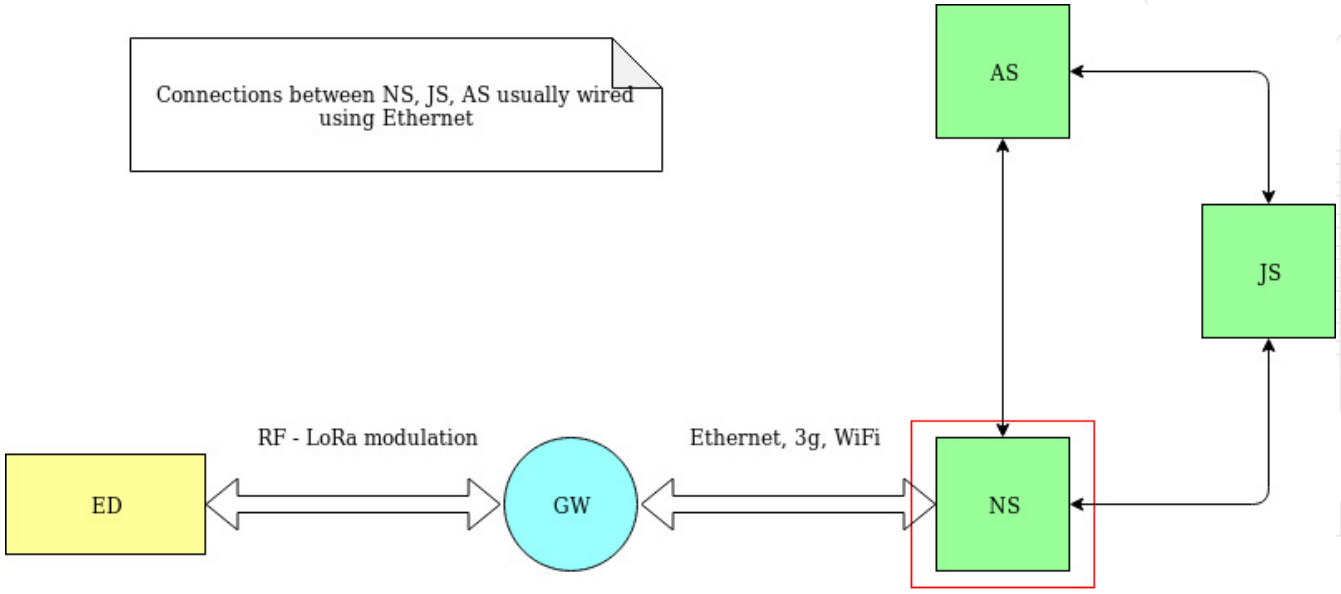

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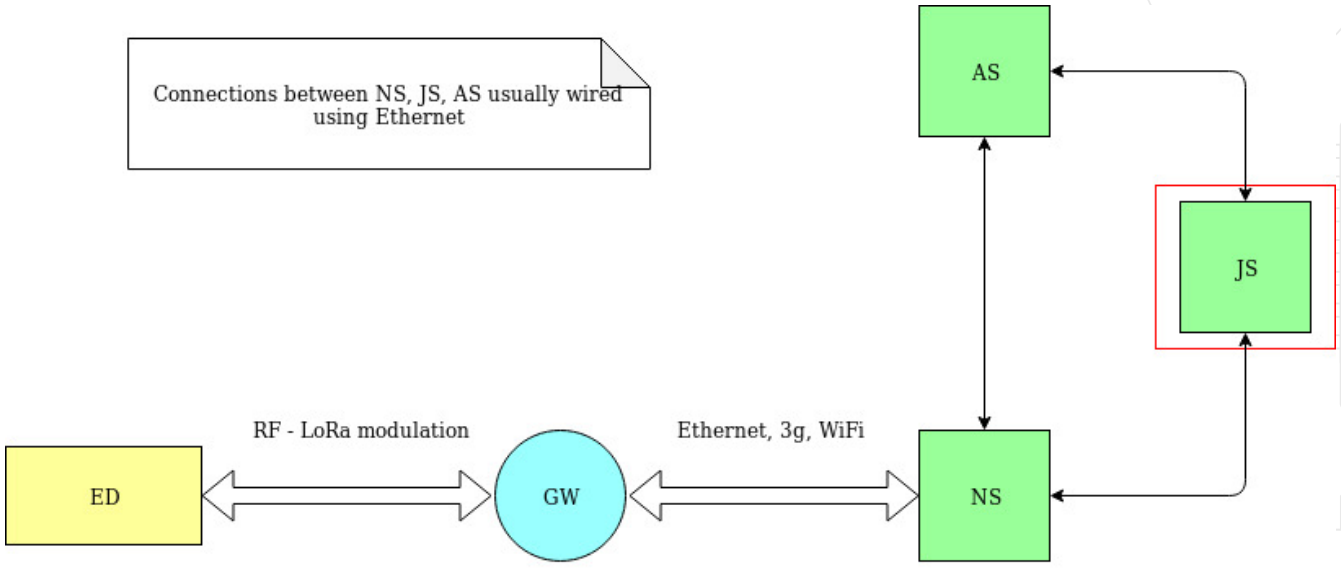

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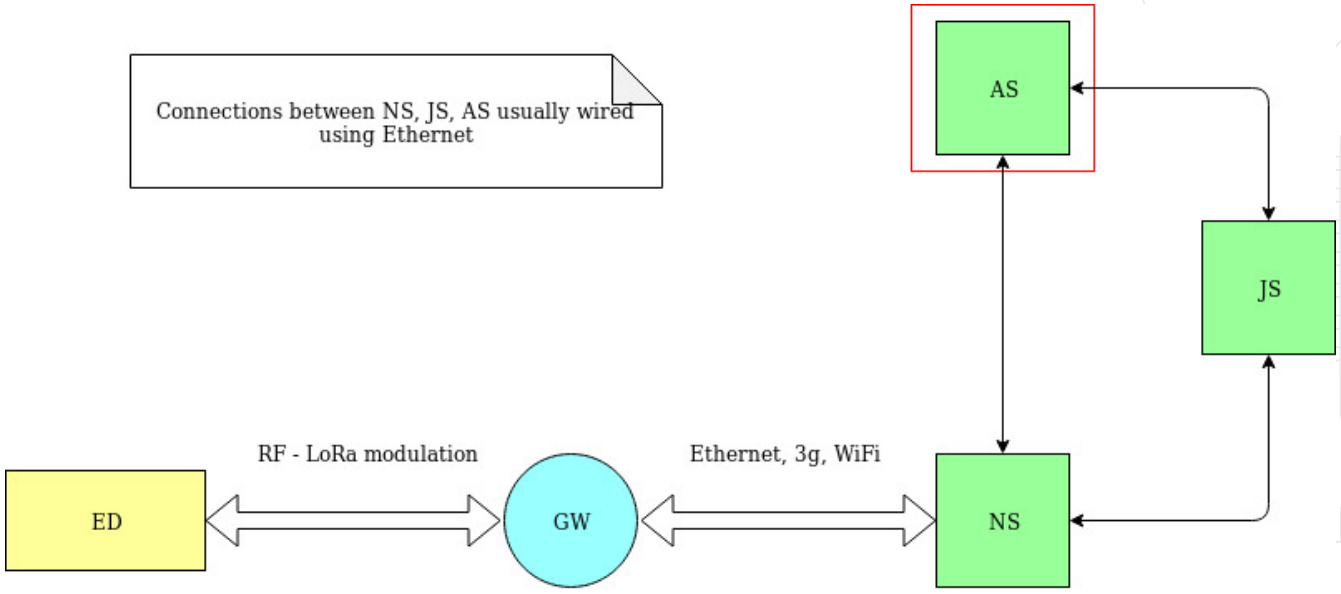

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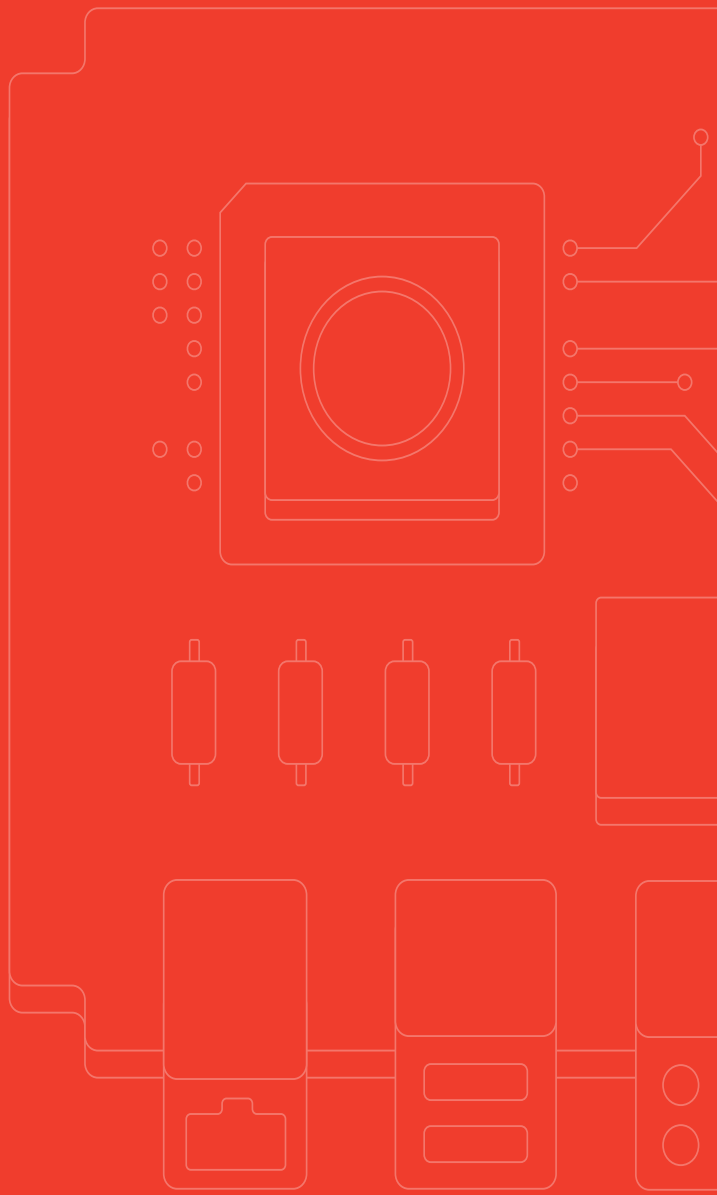
LoRa in RIOT OS

- Using Semtech LoRaMAC library
- Makefile example

```
1  DEVEUI ?= E3632DDB4DE3A955
2  APPKEY ?= 585F77E5C5FD75833B97FC25F7754391
3  # Default radio driver is Semtech SX1276 (used by the B-L072Z-LRWAN1 board)
4  DRIVER ?= sx1276
5  # Default region is Europe and default band is 868MHz
6  REGION ?= EU868
7  # Include the Semtech-loramac package
8  USEPKG += semtech-loramac
9  USEMODULE += $(DRIVER)
10 CFLAGS += -DREGION_$(REGION)
11 CFLAGS += -DDEVEUI=\"$(DEVEUI)\" -DAPPEUI=\"$(APPEUI)\" -DAPPKEY=\"$(APPKEY)
       \"
12 CFLAGS += -DLORAMAC_ACTIVE_REGION=LORAMAC_REGION_$(REGION)
```

Demonstration



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